Jacob Beck

Research Scientist

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Education

- Class of 2025 **University of Oxford**, *United Kingdom*, **DPhil**, Computer Science, Meta-Reinforcement Learning, Multi-Agent Reinforcement Learning, In-Context Learning. Advisor: Prof. Shimon Whiteson
- Class of 2020 **Brown University**, *United States*, **M.S.**, Computer Science, **4.0 GPA**, Human Feedback, Game Theory, Autonomous Vehicles, Reinforcement Learning. Advisor: Prof. Michael Littman, *Thesis*
- Class of 2018 Brown University, United States, B.S., Computer Science, 3.8 GPA. Scholarships
 - 2020–2024 2020 Google DeepMind Doctoral Scholarship

Experience

Full-Time

- 2025 Oracle Labs, Research Scientist,
 - Researching coding agents in the *Machine Learning Research Group*.

Extended Positions

- 2019 Microsoft Research, Predoc, Advisor: Katja Hofmann, Brown's Blog, MSR's Blog,
 - Researched long-term memory in deep RL, with first author publication at ICLR 2020
 - Showed the sensitivity of modern memory approaches to stochasticity in RL
 - Implemented DNC and improved over it by 9%.

2017-2020 Brown University Self-Driving Car Lab, Student Researcher, Advisor: Michael Littman,

- Lead research on learning from human demonstration with human feedback (New Scientist)
- Used Stackelberg game trees for human interaction, with a publication at ICSR 2019
- Created DQN to plan actions for an autonomous car in a Unity.

Internships

Summer 2024 InstaDeep, PhD Research Intern,

- Led research on large language models (LLMs) for protein fitness prediction
- Applied foundation models, in-context learning over related tasks, and fine-tuning
- Published the meta-learning method, *Metalic*, achieving state-of-the-art results on ProteinGym.

Fall 2018 DeepScale, *R&D Intern*,

- Created state-of-the art methods for lane instance segmentation using PyTorch
- Developed heuristic, cluster-based, and end-to-end approaches based on shuffle net.

Summer 2018 Lyft, Software Engineer Intern,

- Worked on behavioral planning at the Level5 autonomous vehicle lab
- Simulated human agents at a stop intersection in C++ $\,$
- Coded an MDP, and solver, to find a policy for AV at a stop intersection .

Summer 2017 Adobe, Data Science Intern,

- Improved forecasting for the Data Science Digital Marketing research team
- Set up the models to re-train online as new data comes in (concurrently)
- Improved team's prediction accuracy by 9%, with only 121 samples per model.

Summer 2015 Pied Piper Robotics LLC, Engineering Intern,

• Designed, 3D printed, programmed, and wired a robot head and neck, using ROS.

Journal Publications

2025 A Tutorial on Meta-Reinforcement Learning Jacob Beck*, Risto Vuorio*, Evan Zheran Liu, Zheng Xiong, Luisa Zintgraf, Chelsea Finn, and Shimon Whiteson Foundations and Trends in Machine Learnining

Conference Publications

- 2025 Offline RLAIF: Piloting VLM Feedback for RL via SFO Jacob Beck RLC Workshop on RL Beyond Rewards: Ingredients for Developing Generalist Agents
- 2025 Metalic: Meta-Learning In-Context with Protein Language Models Jacob Beck, Shikha Surana, Manus McAuliffe, Oliver Bent, Thomas D Barrett, Juan Jose Garau Luis, and Paul Duckworth International Conference on Learning Representations
- 2024 SplAgger: Split Aggregation for In-Context Reinforcement Learning Jacob Beck, Matthew Jackson, Risto Vuorio, Zheng Xiong, and Shimon Whiteson Reinforcement Learning Conference
- 2024 Distilling Morphology-Conditioned Hypernetworks for Efficient Universal Morphology Control Zheng Xiong, Risto Vuorio, **Jacob Beck**, Matthieu Zimmer, Kun Shao, and Shimon Whiteson *International Conference on Machine Learning*
- 2023 Recurrent Hypernetworks are Surprisingly Strong in Meta-RL Jacob Beck, Risto Vuorio, Zheng Xiong, and Shimon Whiteson Neural Information Processing Systems
- 2023 Universal Morphology Control via Contextual Modulation Zheng Xiong, **Jacob Beck**, and Shimon Whiteson International Conference on Machine Learning
- 2023 Trust Region Bounds for Decentralized PPO Under Non-stationarity Mingfei Sun, Sam Devlin, **Jacob Beck**, Katja Hofmann, and Shimon Whiteson *Autonomous Agents and Multiagent Systems* (Best Paper Award)
- 2022 Hypernetworks in Meta-Reinforcement Learning Jacob Beck, Matthew Jackson, Risto Vuorio, and Shimon Whiteson Conference on Robot Learning
- 2021 On the Practical Consistency of Meta-Reinforcement Learning Algorithms Zheng Xiong, Luisa Zintgraf, **Jacob Beck**, Risto Vuorio, and Shimon Whiteson *NeurIPS Meta-Learning Workshop*
- 2021 No DICE: An Investigation of the Bias-Variance Trade off in Meta-Gradients Risto Vuorio, **Jacob Beck**, Gregory Farquhar, Jakob Foerster, and Shimon Whiteson *NeurIPS Deep RL Workshop*

^{*}Contributed equally

- 2020 Stackelberg Punishment and Bully-Proofing Autonomous Vehicles Matt Cooper, Jun Ki Lee, Jacob Beck, Joshua D. Fishman, Michael Gillett, Zoë Papakipos, Aaron Zhang, Jerome Ramos, Aansh Shah, and Michael L. Littman International Conference on Social Robotics
- 2020 AMRL: Aggregated Memory For Reinforcement Learning Jacob Beck, Kamil Ciosek, Sam Devlin, Sebastian Tschiatschek, Cheng Zhang, and Katja Hofmann International Conference on Learning Representations

Academic Services

Speaker

- 2024 ICML Panel, Auto-RL, Panelist, Invited to speak on a *workshop panel* about meta-learning, auto-ML, and LLMs at ICML.
- 2024 **Meta-RL Tutorial**, *Presenter*, Presented a *tutorial* on meta-reinforcement learning at AAAI 2024.
- 2023 **TalkRL Podcast**, *Interview*, Interviewed on the *TalkRL Podcast* to explain meta-reinforcement learning.
- 2023 **Meta-RL Tutorial**, *Presenter*, Presented a *tutorial* on meta-reinforcement learning at AutoML 2023.
- 2021 **ICLR Panel, Philosophy and AGI**, *Organizer*, Organized two *panels* on the the technical and philosophical problems of AGI.

Reviewer

- 2025 Reinforcement Learning Conference, Reviewer.
- 2025 International Conference on Learning Representations, Reviewer.
- 2023 Neural Information Processing Systems, Top Reviewer.
- 2022 NeurIPS Deep RL Workshop, Reviewer.
- 2022 International Conference on Machine Learning, Reviewer.
- 2020 Nature Communications, *Reviewer*.

Teaching and Supervision

- Spring, 2022 **Supervisor**, *University of Oxford*, Matthew Jackson, Hypernetworks in meta-reinforcement learning.
- Fall, 2021 **Co-Supervisor**, *University of Oxford*, Zheng Xiong, On the practical consistency of meta-reinforcement learning algorithms.
 - Fall, 2017 Deep Learning Teaching Assistant, Brown University,
 - Designed, taught, graded material for the graduate deep learning course, CSCI 2470
 - Gave a lecture on implementing sequence-to-sequence translation with attention
 - Designed a lab on recurrent neural networks.

Computer Skills

- Experienced Python, PyTorch, TensorFlow
- Intermediate Java, C++, Unity